

# Hi400i(D)

In order to apply this welding machine and use it safely, be sure to read and fully understand this manual before use, inspection, or repair.





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▶ Before using the welding machine, be sure to read and understand 'Safety Precaution'.

▶ Please keep the Safety Precaution when you use the welding machine since it states important issues regarding the safety for users.

▶ In this manual, the degree of risk is classified into the following three classes for situations that may occur due to the inappropriate usage.





It indicates a situation in which, if used improperly, an imminent risk of death or serious injury to persons may arise.

\* Use the "HAZARD" lettering and the red triangle symbol.





\* Use the "CAUTION" lettering and the yellow triangle symbol.

\* Among the degrees of injury described in the table above, severe injuries mean blindness, burns (hot or cold), fractures, short-term or long-term aftereffect and poisoning that may occur even after hospital treatment.

\* For safety, the installation, operation, maintenance and repair of this equipment must be performed by a qualified person or a person who understands the welding machine well.

\* During the operation, everyone must observe the following, and in particular, children, the elderly, and others with poor judgment must not approach it.

\* Be sure to use the welding machine in a state where safety is guaranteed.

|    | HAZARD   | Electric shock may result in death.  |
|----|--|--|
|    | <ul> <li>Contact with weldin</li> <li>Be careful because<br/>the welding machine</li> <li>When the welding n<br/>the welding machine</li> </ul>  | g parts may cause fatal shock or serious burns.<br>the wire and the work piece are welded when the output of<br>a is generated.<br>nachine power source is on, do not touch the Input power and<br>a internal circuit as it is welded.   |
|    | <ul> <li>When performing set<br/>roller, housing and<br/>touched.</li> <li>Please note that inc</li> </ul>   | mi-automatic or automatic welding, the wire, wire reel, feeding<br>all metal parts are welded and may cause electric shock if<br>correct installation or improper grounding is dangerous.  |
| N. | <ol> <li>Do not touch weld</li> <li>For the case of the<br/>work piece, a quality<br/>with laws and regular</li> <li>For installation and<br/>of the switchgear selepsed. Since the<br/>proceed after confit</li> <li>Use cables with susting<br/>size or with damage</li> <li>Make sure to tight</li> <li>Check the condition<br/>day. Electrical show</li> <li>Do not wrap or lease</li> <li>Use only equipment<br/>being repaired or response<br/>shoes, hard hat, sating</li> <li>Wear moisture-fit</li> <li>Turn off the pow</li> </ol> | ed parts.<br>e welding power source, the jig electrically connected to the<br>ified electrician should perform grounding work in accordance<br>ulations.<br>d maintenance, be sure to turn off the power on the input side<br>switch and perform work after at least 5 minutes have<br>voltage charged in the Internal capacitor may remain,<br>rming that all the charged voltages are discharged.<br>ufficient capacity, and cables which are smaller than the rated<br>ged sheath cannot be used.<br>en the connection part of the Wire and insulate it before use.<br>n of the input and output cables regularly, at least once a<br>ck due to breakdown of cable insulation can result in death.<br>an the cable on your body.<br>nt that is operating normally and do not use equipment that is<br>malfunctioning.<br>ar protective equipments such as protective clothes, protective<br>afety glasses, mask, and gloves.<br>ree, puncture-free insulated gloves.<br>er to all devices when the welding machine is not in use. |

|          | 1   |   |
|----------|---|---|
|          | HAZARD  | Welding may cause fire and explosion.   |
|          | <ul> <li>Spatter during weld</li> <li>Hot work piece imm</li> <li>Welding on airtight<br/>explosion.</li> <li>Welding containers of<br/>explosion.</li> <li>Incomplete contact i<br/>can cause a fire due</li> </ul>  | ing may cause fire or explosion.<br>nediately after welding can cause fire or burns.<br>containers such as pipes, drums and tanks can cause an<br>containing combustible materials such as gasoline can cause an<br>n the current passage, such as incomplete connection of wires,<br>e to heat generated by welding. |
|          | <ol> <li>Clean the area before operation so that the splash spatter does not come into contact with combustible material. If flammable materials cannot be cleaned, cover them with a non-flammable shield.</li> <li>Do not weld near combustible gas.</li> <li>Immediately after welding, be careful not to allow hot work piece access to flammable materials.</li> <li>Fire extinguishers should be installed near the welding workshop to prepare for any eventuality.</li> <li>Do not weld closed containers such as pipes, drums and tanks containing gas inside.</li> <li>Wear fire-resistant, flame-resistant work clothes (top and bottom), gloves, work shoes, face shield, and a hat.</li> <li>Securely tighten and insulate the connections of the wires.</li> <li>For welding of ceiling, floor, and wall, remove the flammable material behind the</li> </ol> |   |
|          | WARNING   | Welding fumes and gases are harmful to the human body,<br>and the accumulation of gas can cause fatal damage and<br>death to the human body.  |
| ری)<br>۲ | <ul> <li>Fumes and gases ar can cause fatal brea</li> <li>1) Shut off the gas v</li> <li>2) Always ventilate in</li> </ul>  | e generated during welding. Exposure to fumes and gases<br>athing difficulties, impairments, or death.<br>alve that is not in use.  |

2) Always ventilate in an enclosed space and wear oxygenator and mask. Also, observe task managers in the vicinity. welding fumes and gases can cause death.

3) Head in the direction of no fume and do not drink as much fume as possible.4) When working inside, install ventilation holes to ensure that fume and gas are

discharged well before working.

5) If ventilation is insufficient, install the dust collector and auxiliary ventilation system.

| <u>.</u> | WARNING  | Electromagnetic fields can harm the operator's body.  |
|----------|--|---|
|          | <ul> <li>Electromagnetic field</li> <li>1) The worker should</li> <li>2) The cardiac pacema<br/>and the welding are</li> <li>3) If the cardiac pacer<br/>machine, consult wi</li> <li>4) Access and welding<br/>instructed by the d</li> </ul> | Is may affect pacemakers.<br>work away from the magnetic field.<br>aker wearer should not be close to the welding power source<br>ea.<br>maker wearer goes near an arc, gouging or resistance welding<br>th your doctor.<br>g are possible only when there are procedures and methods<br>octor in charge. |

| WARNING  | Explosive gas cylinders can cause severe human and property damage.   |
|--|---|
| <ul> <li>Gas cylinders contai<br/>damaged.</li> <li>1) Protect the gas cyl<br/>overheating.</li> <li>2) When installing the<br/>to prevent it from</li> <li>3) Do not weld gas cylind</li> <li>3) Do not hang the to<br/>with the gas cylind</li> <li>5) In order to use the<br/>suitable for the gas</li> <li>6) When opening the<br/>discharge port.</li> <li>7) When using a gas<br/>CO<sub>2</sub> regulator, be suitable for the gas</li> </ul> | n high pressure gas. Use with care as it may explode if<br>linder from arc, spatter, spark, flame, mechanical shock, and<br>gas cylinder, stand it upright and fix it with a string or band<br>falling over.<br>vlinders or do welding or cutting on gas cylinders.<br>orch on the gas cylinder or let the wire come into contact<br>ler.<br>e shield gas properly, use a flowmeter, hose, etc. that are<br>s.<br>valve of the gas cylinder, keep your face away from the<br>regulator, be sure to use a dedicated regulator and for a<br>sure to connect the heater power source before use. |

| ! | CAUTION   | Arc light can cause serious burns to your eyes and skin.  |
|---|---|---|
|   | <ol> <li>In the arc light ger<br/>generated, which da</li> <li>When you see weld<br/>welding faces, safet<br/>ability. (Refer to T</li> <li>Use approved produ-<br/>to the welding helm</li> <li>A light shielding fill<br/>around the arc light</li> <li>Spatter and scatteri<br/>etc. which may cau</li> <li>Use protective glas</li> <li>Prepare for burns to<br/>long-sleeved clothi</li> </ol> | herated during welding, ultraviolet rays and Infrared rays are<br>amages the eyes and skin.<br>ding work or welding, protect your eyes and face by wearing<br>ty glasses, and welding helmets with adequate shielding<br>able 1. Welding Current and Shading Level).<br>ucts for the welding surface and the protective glass attached<br>het.<br>m is installed around the welding work to protect the people<br>t, and be careful not to see the arc light.<br>ng metal are generated during welding, slag removal, grinding,<br>se burns or wounds to the face and body.<br>ses to protect your eyes from spatters and slags.<br>by using protective equipment such as welding leather gloves,<br>ng, leg protectors, and leather materials. |

| Welding Current and Shading Level |              |            |            |              |
|-----------------------------------|--------------|------------|------------|--------------|
| Welding Current                   | 100A or less | 100 - 200A | 300 - 500A | 500A or more |
| Shading Level                     | NO. 9, 10    | NO. 11, 12 | NO. 13, 14 | NO. 15, 16   |

Table 1. Welding Current and Shading Level



CAUTION

#### Hot parts after welding can cause severe burns.

- 1) Do not touch the work piece or torch immediately after welding. Allow the work piece or torch to cool sufficiently before handling.
- 2) Do not touch beads or slags with your bare hands.
- 3) Allow the cooling time before continuing to use the torch or welding torch.

| ! | CAUTION   | Noise can cause hearing impairment.   |
|---|---|---|
|   | <ol> <li>Noise from some v</li> <li>If the noise level</li> </ol> | work and equipment can damage your hearing.<br>is high, wear an approved ear protector. |
|   | I   |   |





- To ensure user's safety, improper use of the product is prohibited.
- We are not responsible for any accidents that when the user arbitrarily changes the design, function, etc to the original welding machine, or uses it differently from the specified usage method such as the original function and rated specifications.
- Please note that places with warning labels are dangerous.
- Po not remove or paint on the warning label.

#### ► Additional Precautions for Installation, Operation and Maintenance

- 1) Welding machine should be installed and grounded according to this manual.
- 2) Do not install in and around flammable places.
- 3) For power source wiring, use a Wire or circuit breaker with a rating higher than the rated power and use it within the rated duty cycle.
- 4) Electromagnetic field energy can cause sensitive interference to electronic equipment such as computers and computer drive controls.
- 5) All equipment near the welding area must be electromagnetically compatible.
- 6) Keep the welding cable length as short as possible, tie it together, and make it as low as possible on the floor to minimize interference.
- 7) If electromagnetic interference continues, use shielded cables, line filters, etc. and measure as you move the position and install it in a suitable location.

### 2. Operating Precautions

For safe and correct use of the product, please read and understand the information below before using the welding machine.

#### ▶ Place of Installation

- 1) Install the welding machine in a flat place without any dust or moist.
- 2) Install the welding machine in a place with adequate airflow, not in an enclosed space.
- 3) Avoid direct sunlight or rain and set the ambient temperature between 10°C and 40°C.
- 4) Do not install flammable objects where the welding machine is located.
- 5) Keep the welding machine at least 30cm from the wall when installing the welding machine.
- 6) When installing two or more welding machine side by side, maintain a distance of more than 30cm between the welding machines.
- 7) Use a gas cylinder for supplying the shielding gas, standing up and fixed to the holder.
- 8) Take measures against wind when there is the influence of wind during welding.



#### Ventilation

During arc welding, the shielding gas is decomposed by the high temperature of the arc, and a small amount of carbon monoxide is generated. For working space of 30m<sup>2</sup> or less, be sure to install a ventilation system for the safety of workers.

#### Protective Equipment

For worker's safety, be sure to wear proper work clothes and protective equipment.

### 2. Operating Precautions

#### Product Movement

The welding machine is equipped with two eye-bolts for movement.

| <u>!</u> | CAUTION  | User may bump into a moving welding machine or the welding machine may fall and cause injury.                     |  |  |
|----------|--|---|--|--|
|          | • When moving or transporting, be sure to secure the welding machine on the transport device and move.   |   |  |  |
|          | <ol> <li>Be sure to disconr</li> <li>Separate the main<br/>welding machine.</li> </ol>   | ect the input power before moving the welding machine.<br>body, wire feeder, cable, torch, etc. before moving the |  |  |
|          | <ul> <li>3) Before moving the welding machine, be sure to check the condition of moving tool.</li> <li>4) The fall of equipment can exclude demage the human back and equipment.</li> </ul>                                      |   |  |  |
|          | <ul><li>5) When using a hoist, double check the safety and capacity of tools and equipment under load.</li></ul>   |   |  |  |
|          | <ul> <li>6) When using a hoist, human access is absolutely prohibited, and the user should adjust it where safety is ensured.</li> <li>7) When moving with a forklift, move as low as possible, and make sure that no</li> </ul> |   |  |  |
| • ~      | <ul><li>a) When moving with a forklift when lifting or lowering the welding machine.</li><li>8) When moving with a forklift, move its hight as low as possible, unless it interferes with other objects.</li></ul>               |   |  |  |
|          | 9) Adjust the width of<br>there is no flow w   | the forklift to match the width of the welding machine, so that<br>hen moving.                                    |  |  |

### 2. Operating Precautions

#### **b** Duty Cycle and Overheat

The duty cycle of welding machine is a percentage of the operating cycle of welding machine that can operate at a given to rated power. The cycle is calculated based on 10 minutes.

For example, if the duty cycle of a 400A welding machine is 60%, it can be used at the rated maximum output (400A, 34V) for 6 minutes welding in a 10-minute cycle and a 4 minute break.





Be sure to use the welding machine in accordance with the duty cycle.

- 1) Excess of the duty cycle causes the temperature overload protection circuit to operate, and the overload circuit does not operate until the temperature inside the overheated welding machine is lowered to the proper temperature.
- 2) If an error is detected due to an overload (temperature) circuit, the power circuit of the welding machine will not operate. It is not a malfunction, so do not disconnect the power switch and wait until it cools down.
- 3) Excess of repeated duty cycle will shorten the damage and lifespan of welding equipment.

#### ▶ When checking the welding machine

- 1) There is a part where high-voltage is applied inside the welding power source. Do not remove the enclosure for any purpose other than repair or inspection.
- 2) If internal inspection of the welding machine is necessary, turn off the power before inspection begins and work after at least 5 minutes or more. The internal capacitors may be charged with voltage. Thus, sufficient time is required before the charged voltage is discharged.

### 3. Product Configuration

#### ► Standard Configuration of the product

Followings are the composition of this welding machine.

#### **Basic Components**

| Item                 | Specification | Quantity |
|----------------------|---------------|----------|
| Welding power source | Hi400i        | 1        |
| Wire feeder          | RF- Hi400     | 1        |
| Interface converter  | Hi-COMM       | 1        |

#### Accessory Components

| Item                      | Standard Specification                   | Quantity |
|---------------------------|--|----------|
| Wire feeder mount bracket | Follow the specification of user's robot | 1        |
| Conduit cable             | ЗМ                                       | 1        |
| Reel stand                | WR- Hi400                                | 1        |
| Straightener              | WR- Hi400                                | 1        |
| Robot torch               | 50SQ                                     | 1        |
| Hi-COMM interface cable   | 6Pr*22AWG, 0.5m                          | 1        |
| Robot interface cable     | 10m                                      | 1        |
| Control cable             | 8m                                       | 1        |
| Sensing cable             | PNCT 2C*1SQ, 5m                          | 1        |
| Output cable              | WCT 50SQ, 8m                             | 2        |

#### ▶ Welding power source rated specification

| Model                      | Hi400i                 |
|----------------------------|------------------------|
| Rated input                | 18.6kVA                |
| Rated input voltage, phase | 3P, 220V / 380V / 440V |
| Rated frequency            | 50/60Hz                |
| Rated output current       | 400A                   |
| Rated load voltage         | 34VDC                  |
| Welding current range      | 30A~ 400A              |
| Welding voltage range      | 10 ~ 36VDC             |
| Max. open circuit voltage  | 80V                    |
| Rated duty cycle           | 60%                    |
| Dimension (W*D*H)          | 316 * 532 * 620(mm)    |
| Weight                     | 45(Kg)                 |
| Process                    | LSM/DCM/PULSE          |

\* Among the external dimension, ( H ) is the size excluding EYE BOLT. (There may be errors in the SIZE and WEIGHT)

#### ► Power Source Equipment

| Hazard  | Electric shock may result in death.   |
|---|---|
| The input power ec<br>installed by a qualit<br>capacity.  | uipment (transformer, wiring breaker, fuse, cable) must be<br>fied electrician, and use the one that is suitable for the rated  |
| <ol> <li>When using an enginput of the welding</li> <li>Install a circuit breater the circuit breaker</li> <li>The allowable rang of the rated input</li> <li>Even in the case of commercial power</li> </ol> | gine generator, use one that is three times or more the rated<br>g machine. (KVA).<br>eaker per each welding power and use the specified capacity of<br>and fuse.<br>ge of input power fluctuation of the welding machine is ±10%<br>voltage.<br>of engine generator, factory self-generation power, or<br>normal output is not possible when the voltage waveform is |
| distorted.<br>5) Do not use the inf   | but power with a noise load.  |

Connection

| HAZARD |
|--------|
|        |

Electric shock may result in death.

- · Before wiring the welding machine, be sure to turn off the power of the circuit protector.
- 1) Connect without gas leakage or poor contact of the conductive parts.
- 2) Be sure to insulate the conductive part where the bare wire is exposed using an insulating material.
- ► Robot Type Wiring



| No. | Item                      | Specification                         |  |
|-----|---------------------------|---------------------------------------|--|
| 1   | Welding power source      | Hi400i                                |  |
| 2   | Wire feeder               | RF- Hi400                             |  |
| 3   | Wire feeder mount bracket | Depend on user's robot specifications |  |
| 4   | Torch                     | Depend on user specifications         |  |
| 5   | Shock sensor              | Depend on user's robot specifications |  |
| 6   | Wire reel stand           | WR- Hi400                             |  |
| 7   | Interface converter       | Hi-COMM                               |  |
| 8   | Conduit cable             | Depend on user specifications         |  |
| 9   | Communication cable       | Welding Power-Wire Feeder             |  |
| 10  | Output/Earth cable        | WCT 50SQ 8m                           |  |
| 11  | Sensing cable             | PNCT 2SQ 5m                           |  |
| 12  | Gas hose                  | 8mm 10m                               |  |
| 13  | Interface converter       | Hi-COMM                               |  |
| 14  | Communication cable       | 10m                                   |  |
| 15  | Communication cable       | Hi-COMM 0.5m                          |  |
| 16  | Gas regulator             | _                                     |  |

#### ► Input Power Connection

| HAZARD  | Electric shock may result in death.<br>Welding may cause fire and explosion.   |
|---|--|
| <ul> <li>Ensure that electric voltage changes.</li> <li>Turn off the circuit</li> <li>If the cable does not set the circuit of the cable does not set the cable</li></ul> | al qualified personnel works on input power connections and<br>breaker for input power before working.<br>ot satisfy the specification, the cable may be overheated and                          |
| <ul><li>be damaged.</li><li>When contacting the the cable that satis</li></ul>  | e damaged cable, electric shock may occur. Be sure to use<br>fies specifications.  |
| 1) Always check the<br>connecting the pow   | power source and voltage with a tester before or after<br>ver.   |
| <ul> <li>2) Grounding work st</li> <li>Perform third cla</li> <li>Perform special more.</li> </ul>  | ipulated by law must be carried out by qualified electricians.<br>ass grounding work for the rated input voltage of 300V or less.<br>third grounding work for the rated input voltage of 300V or |
| <ol> <li>Before connecting<br/>of the welding pov</li> <li>It's not the responsible<br/>with the input pow</li> </ol>   | the power, be sure to read the nameplate and user manual<br>ver.<br>nsibility of ours in case of problems caused by not complying<br>ver, method and capacity specified by the company.          |

#### ► Input Terminal



- 3 220V / 380V / 440V (50/60Hz), Input Spec: 18.6kVA

- Connect the input terminal which is attached to the back of welding machine and the 3-phase power.

#### ► Output Cable Selection

| ! | WARNING  | Electric shock may result in death.  |
|---|--|--|
|   | <ul><li>Use a cable sized f</li><li>Please select and ir</li></ul>   | or the rated power of the welding machine.<br>nstall the cable according to the information below.   |
|   | <ol> <li>Use cables as sho</li> <li>Do not use the ca</li> <li>Use an Insulation<br/>voltage (O.C.V) of</li> <li>Select the welding<br/>machine and the c</li> <li>Do not use damag</li> </ol> | rt as possible. And tie them together.<br>able length too short. It may cause overload.<br>voltage of the welding cable that is greater than the no-load<br>the welding power.<br>g cable according to the maximum voltage of the welding<br>able length connected to the welding machine circuit.<br>ed or worn cables. |
|   | <ul><li>5) This welding mach</li><li>6) Using insufficient</li><li>7) Select the output</li></ul>  | nine is 400A equipment and use 50SQ or more output cable.<br>rated cable may result in poor weldability and cable damaged.<br>cable referring to the table on page 18.   |

#### ► Output Terminal Connection

| WARNING   | Electric shock may result in death.  |
|---|--|
| <ol> <li>Check the symbol<br/>according to the period</li> <li>Fix the output term</li> <li>If the output term</li> <li>Be sure to check</li> <li>Insert the control</li> </ol> | at the output panel of the welding machine and connect it<br>olarity of (+) and (-).<br>minal firmly and securely.<br>inals are loosely fixed, the contact parts may be heated.<br>the fixing state of output terminals before starting welding.<br>cable to the end and fix it. |

| Minimum Cross Section (mm <sup>2</sup> ) | Rated Output Current(A) |                 |  |  |
|--|-------------------------|-----------------|--|--|
| Withinfull Cross Section (Initr)         | 60% Duty Cycle          | 100% Duty Cycle |  |  |
| 10 or more                               | 101                     | 100             |  |  |
| 10 - 16                                  | 139                     | 135             |  |  |
| 16 - 25                                  | 190                     | 180             |  |  |
| 25 - 36                                  | 243                     | 225             |  |  |
| 35 - 50                                  | 316                     | 285             |  |  |
| 50 - 70                                  | 403                     | 355             |  |  |

#### ► Output Cable Selection Table

\* The above table shows the cable size compared to the output current according to IEC 60974-12.

| Length(m)<br>Current(A) | 20 | 30 | 40 | 50  | 60  | 70  | 80  | 90  | 100 |
|-------------------------|----|----|----|-----|-----|-----|-----|-----|-----|
| 100                     | 38 | 38 | 38 | 38  | 38  | 38  | 38  | 50  | 50  |
| 150                     | 38 | 38 | 38 | 38  | 50  | 50  | 60  | 80  | 80  |
| 200                     | 38 | 38 | 38 | 50  | 60  | 80  | 80  | 100 | 100 |
| 250                     | 38 | 38 | 50 | 60  | 80  | 80  | 100 | 125 | 125 |
| 300                     | 38 | 50 | 60 | 80  | 100 | 100 | 125 | 125 |     |
| 350                     | 38 | 50 | 80 | 80  | 100 | 125 |     |     |     |
| 400                     | 38 | 60 | 80 | 100 | 125 |     |     |     |     |

\* The above table is a selection table according to the use of cap tyre cable. When using direct current, the voltage drop is 4(V) or less in cross-section (mm<sup>2</sup>). When using alternating current, use a larger size.

#### Specification of Wire Feeder Control Connector MS3102A- 18- 19P



| PIN | Connection                   | PIN                          |
|-----|------------------------------|------------------------------|
| А   | 48V                          | 48V                          |
| В   | N/C                          | -                            |
| С   | V_FB(+)                      | Output voltage sensing cable |
| D   | CAN_H CAN communication line |                              |
| E   | WCR WCR signal               |                              |
| F   | MOTOR_STOP                   | Motor drive stop signal      |
| G   | V_FB(-)                      | Output voltage sensing line  |
| Н   | CAN_L                        | CAN communication line       |
| J   | ISO_GND GND                  |                              |
| К   | GND                          | GND                          |

\* Please refer to the '6. Product Maintenance' for interface-related connector specifications.

#### ► Welding Power Source



- [1] HMI : Adjust/display the control values/status of the welding machine.
- [2] Power switch : Turns ON/OFF the power of the welding machine.
- [3] Output terminal (+) : Wiring the output cable (to wire feeder).
- [4] Output terminal (-) : Wiring the earth cable (to work piece).
- [5] MS connector : Wiring the control cable of wire feeder.

#### ► Welding Machine Rear Panel



- [1] MS connector1 : Connect Hi-COMM1.
- [2] MS connector2 : Connect Hi-COMM2.
- [3] Input terminal : Connect 3-phase power input cable.
- [4] Circuit protector : Turn on/off the switch to supply main power to the welding machine and protect the circuit. (initialized status of the switch on)

#### 1. Configuration and Function of Display Panel



<Hi400iD Display Panel>

![](_page_20_Figure_0.jpeg)

- [1] HMI : Display set / output / status values.
- [2] Adjustment/Input KNOB : can change the set value / parameter by rotating the KNOB. It can enter or return (or save) into the setting value/parameter switching mode by adjusting the KNOB.
- [3] Wire inching/gas switch : When the switch is operated, wire inching / gas purging operation is executed.
- [4] Menu selection switch : When the switch is operated, screen / menu / setting value / parameter can be selected.
- [5] USB port : Update the firmware of the PCB inside the welding power source using USB.
- [6] Status indication LED : Display the status of welding power.
- POWER : Light on when welding machine is ON. (White)
- WELDING : Light on during welding. (Yellow)
- ERROR : Light on when error is detected. (Red)
- UPDATE : Flicker or light on when USB is connected to the USB port and the firmware is updated. (Green shows when update is completed and ready to remove USB)
- \* For detailed operation of the status Indicator LED during USB UPDATE, refer to the '8. Troubleshooting and Inspection - 3. Product Firmware Update.'

- 2. Screen Configuration Function and Method to Set
- 1) System Booting Screen

![](_page_21_Picture_3.jpeg)

[1] : The system booting starts when welding power source allows to turn on. When the booting starts, the progress bar that displays booting status increases. As progress bar is fully filled, booting is completed and basic setting screen is displayed.

![](_page_21_Picture_5.jpeg)

- [2] Currently set welding conditions are displayed. Display Info JOB No. welding current, welding voltage, wire feeding speed, wire material, wire diameter, operating mode, welding mode, and shielding gas in a selected JOB.
- [3] : Display setting (standby) / output (on welding) welding current. When adjusting the [6] feeding rate after its selection, the setting value of the welding current by the pre-programmed welding database is displayed.
- [4] : Display setting (standby) / output (on welding) welding voltage. When manual is selected, setting method of command voltage can be set. And when synergic is selected, the welding voltage set value is displayed according to the welding current / feeding speed and [5] synergic voltage setting ratio according to the pre-programmed welding database.

- [5] : Display the ratio of set synergic voltage. Command voltage setting method can be set when synergic is selected.
- [6] : Display the setting (standby) / output (on welding) feeding speed. When adjusting [3] the welding current after its selection, the setting value of feeding speed by the pre-programmed welding database is displayed.
- [7] : Display the holding time of the welding power source on. Form [ Hour : Min : Sec ]
- [8] : Display the operating status by operating gas and inching switches. During operation, the corresponding icon is highlighted.
- [9] : Navigation point bar that places current screen out of entire menu screen.
- \* Available to select [3] welding current, [4] welding voltage, [6] feeding speed by operating

switch. Selected items's color and value can be changed by rotating the KNOB.

\* The parameters and adjustable ranges that can be adjusted within the setting screen are listed in the table below.

| Parameter [Unit]      | Min.  | Max. | Adjustment Unit |
|-----------------------|-------|------|-----------------|
| Welding Current [A]   | 30    | 400  | 1               |
| Welding Voltage [V]   | 10.0  | 36.0 | 0.1             |
| Synergic              | - 5.0 | 5.0  | 0.1             |
| Feeding Speed [m/min] | 0.9   | 18.0 | 0.1             |

3) JOB Selection Screen

![](_page_22_Figure_11.jpeg)

- [10] : Display the currently set Job No. The range of selectable Job No. is 1 to 100.
- [11] : Welding conditions set in the selected Job can copy to other Jobs. Selection of the Job No. to copy is available.
- [12] : Welding conditions set in the selected Job can be copied to other Jobs. The welding conditions of the Job selected in [11] can be copied and saved to this Job No.
- [13] : After setting the conditions [11], [12] for copying and saving Jobs, select this to execute.
- [14] : Welding conditions stored in all Job No. are initialized (factory default setting). When initializing settings, the values are changed as shown in the table at below.

| Parameter [Unit]         | Initial value   | Parameter [Unit]       | Initial value   |
|--------------------------|---|------------------------|---|
| Welding current<br>[A]   | 200   | Welding voltage<br>[V] | Database setting value<br>in accordance with<br>welding current |
| Feeding speed<br>[m/min] | Database setting value<br>in accordance with<br>welding current | Synergic               | 0.0   |
| Wire material            | FE-Solid  | Wire diameter<br>[mm]  | □1.2  |
| Operation mode           | 1T  | Welding mode           | LSM   |
| Shielding gas            | CO <sub>2</sub> 100%  | Job No.                | Current setting value   |

- \* Menu items can be selected by operating
- \* In the selected menu, press the KNOB to enter the setting change mode, and adjust the KNOB to adjust and save the setting value. After setting, press the KNOB again to cancel the setting change mode. In menu [13],[14], the function is executed when it is released after entering it.

#### ! Note: After entering the setting change mode, unavailable to select or move to other menus unless there is releasing of the change mode.

#### 4) Job Setting Screen

![](_page_23_Figure_6.jpeg)

- [15] : Available to select welding mode.
- [16] : Available to select wire diameter.
- [17] : Available to select wire materials.
- [18] : Available to select shielding gas.
- [19] : Available to select command voltage setting method.
- [20] : Available to change arc characteristic adjustment ratio. It displays initial value(0) and adjustable range at the right side of menu(-50  $\sim$  50)
- [21] : Selection of welding setting without programming welding database([15],[16],[17],[18]) displays the 'no database' pop- up window, and welding is unavailable. Selection of the settings with welding database, the pop- up window disappears and welding can be performed.

\* Explanation of adjustable parameter and setting value in the Job setting screen are shown in the table at below.

| Parameter [Unit]       | Setting Value   |  |  |  |
|------------------------|---|--|--|--|
|                        | 1) LSM mode : Low spatter welding mode  |  |  |  |
|                        | * Example of welding wave   |  |  |  |
| Welding mode           | 2) DCM mode : General DC welding mode   |  |  |  |
|                        | * Example of welding wave   |  |  |  |
|                        | 3) PM mode: Pulse welding mode (mode will be added)                                 |  |  |  |
|                        | 4) DPM mode: Double pulse welding mode (mode will be added)                         |  |  |  |
| Wire diameter [mm]     | 0.8, 0.9. 1.0, 1.2, 1.4, 1.6  |  |  |  |
| Wire material          | Fe-Solid, Fe-Cored, STS-Solid, STS-Cored, AL-Soft, AL_Hard,<br>CuSi, CuMg, SP1, SP2 |  |  |  |
|                        | 1) CO <sub>2</sub> 100%   |  |  |  |
| Shielding gas          | 2) Ar 80% + CO <sub>2</sub> 100%  |  |  |  |
| Shielding gas          | 3) Ar 98% + CO <sub>2</sub> 2%  |  |  |  |
|                        | 4) Ar 100%  |  |  |  |
| Voltage setting method | Manual, Synergic  |  |  |  |
|                        | 1) Adjustment range : -50 $\sim$ 50 (Initial value : 0)                             |  |  |  |
|                        | 2) Adjustment unit : 1  |  |  |  |
|                        | $\star$ + : Hard arc, amount of Spatter $\uparrow$ , ease high-speed welding        |  |  |  |
|                        | * 0 : Reference Value   |  |  |  |
| Arc Characteristic     | $\star$ - : Soft arc, amount of spatter $\downarrow$ , ease low-speed welding       |  |  |  |
|                        | +   |  |  |  |

- \* Menu items can be selected by operating
- \* In the selected menu, press the KNOB to enter the setting change mode, and rotate the KNOB to adjust the setting value. After setting, press the KNOB again to cancel the setting change mode.
- ! Note: After entering the setting change mode, unavailable to select or move to other menus unless there is releasing of the change mode.

#### 5) Welding Start Parameters Setting Screen

|       | Job                                       | 100A       | 15.1V    | 2.1r       | n/min    | Fe-Solid  | Ø 1.2mm  |
|-------|---|------------|----------|------------|----------|-----------|----------|
|       | No. 1                                     | 1-S        | tep      | LSM        | Ar.805   | %+CO2.20% |          |
|       | Weld St                                   | tart       |          |            |          |           |          |
| [22]- | = = • SI                                  | ow down    | speed    | : 0        |          | (Def : 0  | , -5050) |
| [23]- | a Pre-flow time : Oms (0-10,000)          |            |          |            |          |           | -10,000) |
| [24]- | 😑 😅 🛛 Hot-Start current : 400A (0-600     |            |          |            |          | (0~600)   |          |
| [25]- | - 📼 📼 Hot-Start time : 0 (Def : 0, -15-15 |            |          |            |          | , -15~15) |          |
| [26]- | = = • He                                  | ot-Start e | end dete | ection Lv. | : 500DAC |           | 0~1,023) |
|       |   |            |          |            |          |           |          |
|       |   |            |          | 000        |          |           |          |

[22] : Set the wire slow down feeding speed.
[23] : Set the shielding gas pre-flow time.
[24] : Set the HOT START current.
[25] : Set the HOT START time.

- [26] : Set the HOT START ending detection level.
- \* Information on the setting value of the adjustable parameter within the welding start parameters setting screen are shown in the table at below.

| Parameter [unit]                            | Initial | Min. | Max.   | Adjustment unit |
|---|---------|------|--------|-----------------|
| HOT - START current [A]                     | 400     | 0    | 600    | 1               |
| HOT - START time [ms]                       | 0       | - 15 | 15     | 1               |
| HOT - START ending detection level<br>[DAC] | 500     | 0    | 1,023  | 1               |
| Wire slowdown feeding speed [m/min]         | 0       | - 50 | 50     | 1               |
| Shielding gas pre- flow time [ms]           | 20      | 0    | 10,000 | 1               |

\* Menu items can be selected by operating

\* In the selected menu, press the KNOB to enter the setting change mode, and rotate the KNOB to adjust the setting value. After setting, press the KNOB again to cancel the setting change mode.

! Note: After entering the setting change mode, unavailable to select or move to other menus unless there is releasing of the change mode.

6) Welding Crater Parameters Setting Screen

|       | Job  | 100A      | 15.1V       | 2.1m/n                            | nin I    | Fe-Solid    | Ø 1.2mm  |
|-------|--|-----------|-------------|-----------------------------------|----------|-------------|----------|
|       | No. 1<br>Crater                            | 1-St      | tep i.      | SM                                | Ar.80%+C | 02.20%      |          |
| [27]- |  | ater weld | ling curre  | nt : 100A                         |          | (           | 30~400)  |
| [28]- | Crater welding voltage : 15.1V (10.0~40.0) |           |             |                                   |          |             | .0~40.0) |
| [29]- | Crater feeding speed : 2.1m/min (0.9-18.0) |           |             |                                   |          | .9-18.0)    |          |
| [30]- | Operating mode : 1-Step                    |           |             |                                   |          |             |          |
| [31]- | Cra  | ater syne | ergic volta | ige : 0.0                         |          | (Def : 0, - | 5.0~5.0) |
|       |  |           |             |                                   |          | 211221      |          |
|       |  |           | •••         | $\bullet \bullet \bullet \bullet$ |          |             |          |

- [27] : Set the crater welding current. Display the crater welding current by pre-programmed welding database when selecting and adjusting the crater feeding speed[29].
- [28] : Set the crater welding voltage. When manual is selected, command voltage setting method can be set. When synergic is selected, display the setting value of crater welding voltage by pre-programmed welding data base according to the welding current/feeding speed and [31] crater synergic voltage setting ratio.
- [29] : Set the crater feeding speed. Displays crater setting value of feeding speed by preprogrammed welding database when selecting and adjusting the crater welding current.
- [30] : Select the operating mode. Operation sequence in accordance with operating mode is as follows.

![](_page_26_Figure_7.jpeg)

\* 1-Step

Pre-flow time, 2 No load output period, 3 start welding period, 4 Main welding period,
 6 Post-flow time

\* 2-Step

![](_page_27_Figure_2.jpeg)

Pre-flow time, ② No load output period, ③ Start welding period, ④ Main welding period,
 ⑤ Crater welding period, ⑥ End welding period, ⑦ Post-flow time

#### \* 4-Step

![](_page_27_Figure_5.jpeg)

- Pre-flow time, 2 No load output period, 3 Start welding period, 4 Main welding period,
   5 End welding period, 6 Post-flow time
- [31] : Set the ratio of set crater welding synergic voltage. Command voltage setting method can be set when synergic is selected.

\* The parameters and adjustment ranges that can be adjusted within the crater parameters setting screen are shown in the table below.

| Parameter [Unit]                      | Min.   | Max.   | Adjustment Unit |
|---------------------------------------|--------|--------|-----------------|
| Crater welding current [A]            | 30     | 400    | 1               |
| Crater welding voltage[V]<br>(Manual) | 10.0   | 36.0   | 0.1             |
| Crater feeding speed [m/min]          | 0.9    | 18.0   | 0.1             |
| Operating mode                        | 1-Step | 4-Step | -               |
| Crater synergic voltage               | - 5.0  | 5.0    | 0.1             |

- \* Menu items can be selected by operating
- \* In the selected menu, press the KNOB to enter the setting change mode, and rotate the KNOB to adjust the setting value. After setting, press the KNOB again to cancel the setting change mode.
- ! Note: After entering the setting change mode, unavailable to select or move to other menus unless there is releasing of the change mode.
- 7) Welding End Parameters Setting Screen

![](_page_28_Figure_7.jpeg)

- [32] : Adjust Burn-Back output size to adjust the size of the end of wire when welding is ended.
- [33] : Adjust Burn-Back output time to adjust the size of the end of wire when welding is ended.
- [34] : Adjust Ant-Stick output to release the fusion between the wire and the work piece after welding is ended.
- [35] : Adjust Anti-Stick output time to release the fusion between the wire and the work piece after welding is ended.
- [36] : Set the post-flow time.

\* Information on the setting value of the adjustable parameter within the welding end parameters setting screen are shown in the table at below.

| Parameter [Unit]                 | Initial | Min. | Max.   | Adjustment Unit |
|----------------------------------|---------|------|--------|-----------------|
| Burn- Back output [%]            | 20      | 0    | 100    | 1               |
| Burn- Back output [ms]           | 20      | 0.0  | 200    | 1               |
| Anti- Stick output voltage [DAC] | 500     | 0    | 1,023  | 1               |
| Anti- Stick output time [ms]     | 10      | 0.0  | 100    | 0.1             |
| Post- flow Time [ms]             | 200     | 0    | 10,000 | 1               |

- \* Menu items can be selected by operating Switch.
  - \* In the selected menu, press the KNOB to enter the setting change mode, and rotate the KNOB to adjust the setting value. After setting, press the KNOB again to cancel the setting change mode.
  - ! Note: After entering the setting change mode, unavailable to select or move to other menus unless there is releasing of the change mode.
  - 8) System Setting Parameters Screen

![](_page_29_Figure_7.jpeg)

[37] : Users authority of welding power source can be changed. According to users' authority, setting parameters screen of internal control parameters can be activated or non-activated. Changes in accordance with users' authority are as follows.

| Users Authority | Initial Setting | Displayed Items  |  |
|-----------------|-----------------|--|--|
| Customer Level  | 0               | Detailed parameter setting inactive  |  |
|                 |                 | Welding Start, End, Waveform Control detailed Parameter<br>Setting Screen non-active |  |
| Engineer level  |                 | * Information on detailed setting parameters is provided                             |  |
|                 |                 | separately by the manufacturer   |  |

In order to change users authority (Engineer level), password is required. If you select Engineer Level in this menu and release the setting change mode, the [43] password input screen is activated.

After entering the 4-digit password given by the maker using the switch and KNOB select the required items [44]~[45] to activate/deactivate the authority. To cancel to enter the password input screen, select [46] Back.

# ! Note : Inappropriate setting of detailed parameters that is set at Engineer Level may cause serious abnormalities in welding performance. Only a professional or a person authorized by the manufacturer should operate it, and the manufacturer is not responsible for free service for any abnormality or malfunction of the system due to improper change of this setting by an unauthorized person.

- [38] : User can select a device to set welding current, welding voltage, and wire feeding speed by welding power source. Devices that can be set are HMI, Hi-COMM, and wire feeder, and even if these devices are connected to the welding power source in duplicate, only the setting value selected in this setting can be recognized at the welding power source.
- [39] : User can select a device that sets the system setting parameter with welding power source. Devices that can be set are HMI, Hi-COMM, and wire feeder, and even if these devices are connected to the welding power source in duplicate, only the setting value of the device selected can be recognized by the welding power source.
- [40] : User can select a device to set the welding setting parameter by welding power source. Devices that can be set are HMI, Hi-COMM, and wire feeder, and even if these devices are connected to the welding power source in duplicate, only the setting value of the device selected can be recognized at the welding power source.
- [41] : User can select the operation control mode of the cooling fan. When 'auto control' is selected, the cooling fan operates according to the set temperature in [42], and when 'always' is selected, the cooling fan always operates when the welding power source is 'ON'.
- [42] : When [41] is 'auto control', you can set the temperature at which the fan operates. If the temperature of a specific part inside the welding power source is above this set temperature, the cooling fan operates, and when it falls below the set temperature, the cooling fan stops.

\* The information on the setting values of the adjustable parameters within the welding system setting screen is shown in the table below.

| Name                           | Initial  | Min.                                | Max. | Adjustment<br>Unit | Unit   |
|--------------------------------|--|-------------------------------------|------|--------------------|--------|
| A, V, m/min setting unit       | HMI HMI, Hi-COMM1, Hi-COMM2, Wire              |                                     |      | Feeder             |        |
| System parameters setting unit | System parameters setting unit HMI HMI, Hi-COM |                                     |      | COMM2, Wire        | Feeder |
| Welding parameter setting unit | НМІ  | HMI, Hi-COMM1, Hi-COMM2, Wire Feede |      |                    | Feeder |
| Fan control mode               | Auto<br>Control                                | Always, Auto Control                |      |                    |        |
| Fan control temp. of auto mode | 40   | 0                                   | 100  | 1                  | Ĉ      |

9) System Status / Information Parameters Display Screen

![](_page_32_Figure_2.jpeg)

![](_page_32_Figure_3.jpeg)

- [47] : Display accumulated operation time of DC LINK relay of power converter. [Hour : Min : Sec]
- [48] : Display accumulated operation time of cooling fan. [ Hour : Min : Sec ]
- [49] : Display accumulated operation time of solenoid valve. [ Hour : Min : Sec ]
- [50] : Display accumulated operation time of welding sequence. [ Hour : Min : Sec ], welding sequence: the cycle that completes every programmed operation after recognizing start ON->OFF signal from welding power source.
- [51] : Display accumulated operation time of WCR. [ Hour : Min : Sec ], WCR : Status in which the welding power source recognizes that welding (in which the welding current is detected) is in progress.
- [52] : Display accumulated operation time of feeding motor. [ Hour : Min : Sec ]
- [53] : Display ON/OFF accumulated number of welding power source. When welding power source turns OFF to ON, number is accumulated.
- [54] : Display accumulated operation number of DC LINK relay of power converter. When it turns OFF-> On, number is accumulated.
- [55] : Display accumulated operation number of cooling fan. When it turns OFF->ON, the number is accumulated.

- [56] : Display accumulated operation number of solenoid valve. When it turns OFF->ON, the number is accumulated.
- [57] : Display accumulated operation number of stick check (Detection between wire and work piece). When stick check is on, the number is accumulated.
- [58] : Display accumulated occurred number of welding output load. When it turns OFF->On, the number is accumulated.

\* Please refer to "6. Product Maintenance' of this manuel for the use of information.

10) Firmware Information Display Screen

![](_page_33_Picture_6.jpeg)

Available to check the firmware version information of the welding system driving PCB.

11) Error Log Display Screen

| No   | .1         | 1-Step   | į.  | LSM        | Ar.809     | 6+C  | 02.20%     |          |   |
|------|------------|----------|-----|------------|------------|------|------------|----------|---|
| Erro | or Log     | Welding  | ma  | chine ope  | ration tir | ne : | [00:00:00] | ]        |   |
| No.  | Error code | Run time | No: | Error code | Run time   | No.  | Error code | Run time |   |
| 1.   |            |          | 11. |            |            | 21.  |            |          |   |
| 2.   |            | 53       | 12. |            |            | 22.  |            |          |   |
| 3.   |            |          | 13. |            |            | 23.  |            |          |   |
| 4.   |            |          | 14. |            |            | 24.  |            |          |   |
| 5.   |            |          | 15. |            |            | 25.  |            |          | 0 |
| 6.   |            | - 23     | 16. |            |            | 26.  |            |          | 6 |
| 7.   |            | ÷.       | 17. |            |            | 27.  |            |          |   |
| 8.   |            | -        | 18. |            |            | 28.  |            |          |   |
| 9.   |            | ÷.;      | 19. |            |            | 29.  |            |          |   |
| 10.  |            | ÷.,      | 20. |            |            | 30.  |            |          |   |

It displays error codes generated by operating time during welding machine operation. 100 error codes are allowed to record, and when the number of records is exceeded, error codes that occurred first are deleted. Error codes are recorded in the order of the most recent occurrence, error code, and operation time.

When there is an error during the operation of welding machine, a error indicator lamp(Red) of HMI lights on and a beep sound comes to indicate that an error has occurred. At this time, the user use the screen to move into the error log screen to check the error code, the error indicator lamp and the beep sound turn off.

If you ignore the error log screen or apply a welding torch signal while the cause of the error is not resolved, the error is repeated.

## \* Please refer to '8. Troubleshooting and Inspection' of this manuel regarding error log use and action.

| HYUNDAI(1/0) |         |                          |                            |  |  |
|--------------|---------|--------------------------|----------------------------|--|--|
| Robot Out    | Current | Voltage<br>(Manual mode) | Voltage<br>(Synergic mode) |  |  |
| 0.0 V        | 30 A    | 10.0 V                   | - 50                       |  |  |
| 1.7 V        | 83 A    | 14.3 V                   | - 36                       |  |  |
| 3.4 V        | 136 A   | 18.6 V                   | - 21                       |  |  |
| 5.1 V        | 189 A   | 22.9 V                   | - 7                        |  |  |
| 6.9 V        | 241 A   | 27.1 V                   | 7                          |  |  |
| 8.6 V        | 294 A   | 31.4 V                   | 21                         |  |  |
| 10.3 V       | 347 A   | 35.7 V                   | 36                         |  |  |
| 12.0 V       | 400 A   | 40.0 V                   | 50                         |  |  |

#### 3. Setting of Robot Parameters (Setting Current, Voltage)

| YASKAWA(I/O) |         |                          |                            |  |  |  |
|--------------|---------|--------------------------|----------------------------|--|--|--|
| Robot Out    | Current | Voltage<br>(Manual mode) | Voltage<br>(Synergic mode) |  |  |  |
| 0.0 V        | 30 A    | 10.0 V                   | 50                         |  |  |  |
| 2.0 V        | 83 A    | 14.3 V                   | 64                         |  |  |  |
| 4.0 V        | 136 A   | 18.6 V                   | 79                         |  |  |  |
| 6.0 V        | 189 A   | 22.9 V                   | 93                         |  |  |  |
| 8.0 V        | 241 A   | 27.1V                    | 107                        |  |  |  |
| 10.0 V       | 294 A   | 31.4 V                   | 121                        |  |  |  |
| 12.0 V       | 347 A   | 35.7 V                   | 136                        |  |  |  |
| 14.0 V       | 400 A   | 40.0 V                   | 150                        |  |  |  |

#### 1. Schematic Diagram - Hi400i 220V I/O Interface

![](_page_35_Figure_2.jpeg)

#### 1. Schematic Diagram - Hi400i 220V I/O Interface

![](_page_36_Figure_2.jpeg)

#### 2. Schematic Diagram - Hi400i 220V Serial Interface

![](_page_37_Figure_2.jpeg)

EXTERNAL UNITS(ROBOT, PLC, PC NETWORK ...)

#### 2. Schematic Diagram - Hi400i 220V Serial Interface

![](_page_38_Figure_2.jpeg)

#### 3. Hi- COMM IO Interface (PCB6) Detailed Schematic Diagram D- SUB 25PIN FEMALE (25pin)

![](_page_39_Picture_2.jpeg)

| No. | PIN name            | Explanation  |
|-----|---------------------|--|
| 1   | ROBOT_GND           | +24VDC power GND connected to the robot controller     |
| 2   | MAIN_WELD_SET_A     | Analog input signal for main welding voltage command   |
| 3   | CRATER_WELD_SET_A   | Analog input signal for crater welding voltage command |
| 4   | WELD_OUT PUT_A      | Welding feedback current analog output signal          |
| 5   | /T ORCH_SIG         | Torch ON / OFF input signal                            |
| 6   | /INCHING_SIG        | Inching ON / OFF input signal                          |
| 7   | /R-INCHING_SIG      | R-Inching ON / OFF input signal                        |
| 8   | /GAS_CHECK_SIG      | Gas check ON / OFF input signal                        |
| 9   | /JOB_BIN0_SIG       | JOB number selection ON / OFF input signal0            |
| 10  | /JOB_BIN2_SIG       | JOB number selection ON / OFF input signal2            |
| 11  | ROBOT_RELAY_GND     | Relay GND for digital output                           |
| 12  | WELDER_ERROR_STATUS | Welding machine error status output signal             |
| 13  | WIRE_STICK-         | WIRE_STICK-  |
| 14  | ROBOT_+24V          | +24VDC connected to the robot controller               |
| 15  | MAIN_WELD_SET_V     | Analog input signal for main welding voltage command   |
| 16  | CRATER_WELD_SET_V   | Analog input signal for crater welding voltage command |
| 17  | WELD_OUT PUT_V      | Welding feedback voltage analog output signal          |
| 18  | /CRATER_SIG         | Crater sequence ON / OFF input signal                  |
| 19  | /STICK_CHECK_SIG    | Stick check sequence ON / OFF input signal             |
| 20  | /ROBOT_ERROR_SIG    | Robot error status input signal                        |
| 21  | /JOB_BIN1_SIG       | JOB number selection ON / OFF input signal1            |
| 22  | /JOB_BIN3_SIG       | JOB number selection ON / OFF input signal3            |
| 23  | WELD_WCR_STATUS     | WCR status output signal                               |
| 24  | STICK_CHECK_STATUS  | Stick status output signal                             |
| 25  | WIRE_STICK+         | WIRE_STICK+  |

#### 4. Hi- COMM Serial Interface(PCB6) Detailed Schematic Diagram D- SUB 15PIN FEMALE (15pin)

![](_page_40_Picture_2.jpeg)

| PIN # | PIN name        | Explanation   |
|-------|-----------------|---|
| 1     | ROBOT_GND       | +24VDC power GND connected to the robot controller            |
| 2     | _               | _   |
| 3     | ROBOT_CAN_L     | CAN communication signal connected to the robot controller    |
| 4     | ROBOT_RS232_T X | RS-232 communication signal connected to the robot controller |
| 5     | ROBOT_RS485_L   | RS-485 communication signal connected to the robot controller |
| 6     | ISO2_GND        | Isolation GND for Hi-COMM communication                       |
| 7     | _               | _   |
| 8     | WIRE_STICK-     | WIRE_STICK-   |
| 9     | ROBOT_+24V      | +24VDC connected to the robot controller                      |
| 10    | _               | _   |
| 11    | ROBOT_CAN_H     | CAN communication signal connected to the robot controller    |
| 12    | ROBOT_RS232_RX  | RS-232 communication signal connected to the robot controller |
| 13    | ROBOT_RS485_H   | RS-485 communication signal connected to the robot controller |
| 14    | _               | _   |
| 15    | WIRE_STICK+     | WIRE_STICK+   |

5. Hi400iD DeviceNet Interface(MC2, MC3) Detailed Schematic Diagram

![](_page_41_Picture_2.jpeg)

| 핀번 | 핀명      | 설명   |
|----|---------|--|
| Α  | V-      | +24VDC power GND connected to the robot controller |
| В  | V+      | +24VDC connected to the robot controller           |
| F  | CAN L   | CAN communication signal connected to the robot    |
| -  |         | controller   |
| F  |         | CAN communication signal connected to the robot    |
| F  | CAN H   | controller   |
| G  | ISO_GND | Isolation GND for communication                    |

- 6. Parts List Hi400i Welding Power Source

![](_page_42_Figure_3.jpeg)

| Signal  | Part name    | Part number | Specification          | QTY | Note      |
|---------|--------------|-------------|------------------------|-----|-----------|
| C1      | Capacitor    | 45000423    | 10uF/630V              | 1   |           |
| C2,3    | Capacitor    | 45000439    | 103/1kV                | 2   |           |
| СР      | Protector    | 45000206    | DCP73BH 73A 380V       | 1   |           |
| CT1     | CT           | 45000424    | CT 800T                | 1   |           |
| CT 2    | CT           | 45000421    | TM2A300-04DA15         | 1   |           |
| D1      | Diode        | 40006421    | MDS100A 1600V          | 1   |           |
| D2 ~ D8 | Diode        | 40005610    | EST 100BN40S           | 7   |           |
| F1      | Fuse         | 40005485    | JR61-100A              | 1   |           |
| F2      | Fuse         | 45000507    | 500VAC/DC 5A ø10x38mm  | 1   |           |
| FAN1,2  | Fan          | 45000437    | NMB 12038VA-24R-EL-00  | 2   |           |
| L1      | Coil         | 45000485    | CH610125x2             | 1   |           |
| L3,4    | Ferrite core | _           | 51.5x13.5              | 2   |           |
| L5      | Reactor      | 45000484    | CH610125x3             | 1   |           |
|         | MORET        | 45000530    | IXFN150N65X2           | 8   | 220V      |
|         | MUSFEI       | 40005839    | IXFN56N90P             | 8   | 380V/440V |
| MC1     | Connector    | 45000492    | MS3102A 18-19P         | 1   |           |
| MC2,3   | Connector    | 45000492    | MS3102A 20-27P         | 2   |           |
|         | Filter       | 45000520    | ET3AA-2100 / 250V 100A | 1   | 220V      |
| IN F    | Filler       | 40004373    | ET3AA-4040 / 450V 40A  | 1   | 380V/440V |
| PCB1    | PCB          | 45000468    | HICM 500_01            | 1   |           |
| DCD2    |              | 45000469    | HICM 500_02            | 1   | 220V      |
| PCD2    | PCB          | _           | HICM 500_06            | 1   | 380V/440V |
| DCD2    |              | 45000470    | HICM 500_03            | 1   | 220V      |
| FCBS    | FCD          | _           | HICM 500_03            | 1   | 380V/440V |
| PCB4    | PCB          | 45000528    | HICM 500_04            | 1   |           |
| PCB5    | PCB          | 45000473    | HAZD500_01             | 1   |           |
| PCB7    | PCB          | 45000529    | HICM 500_05            | 1   |           |
| PCB8    | PCB          | 45000471    | HACD500_01             | 1   |           |
| PCB9    | PCB          | 45000472    | HACD500_02             | 1   |           |
| PCB10   | PCB          | 40005832    | HICE12-SNUBBER         | 1   |           |
| Q1      | IGBT         | 45000006    | 1MBI 900V-120-50       | 1   |           |
| R1      | Resistor     | 45000512    | 2ohm 150N              | 1   |           |
| R2      | Resistor     | 45000513    | 500ohm 150N            | 1   |           |
| SW/1    | Switch       | 45000510    | Push-Latch, ø25        | 1   | 220V      |
| 5001    | Switch       | _           | Push-Latch, ø25        | 1   | 380V/440V |
| т1      | Transformer  | 45000483    | 220V                   | 1   | 220V      |
| • •     | Tansionnei   | -           | 380V/440V              | 1   | 380V/440V |
| T2      | Transformer  | 45000491    | Auxiliary TR 50VA      | 1   |           |
| TB1     | Terminal     | 40003435    | 3Ph                    | 2   |           |
| T B3,4  | Terminal     | 40003443    | ALPHA                  | 2   |           |
| TNR1 ~  | Curprosect   | 45000438    | TNR(10V471K)           | 4   | 220V      |
| TNR4    | Surpressor   | _           | TNR(14V821K)           | 4   | 380V/440V |
| 1/04    | 01400        | 45000531    | TKS220A500V24-R2       | 1   | 220V      |
| VS1     | SMPS         | 45000068    | TKS440A500V24-R2       | 1   | 380V/440V |

#### 7. Periodic Maintenance according to using time/number

When accumulated operation time of cooling fan exceeds 32,000 hours, recommend to replace FAN1 and FAN2.

When ON/OFF accumulated number of cooling fan exceeds 680,000, recommend to replace RL1 of PCB1.

When ON/OFF accumulated number of DC LINK relay exceeds 100,000, recommend to replace PCB2.

When accumulated number of stick check exceeds 2,700,000, recommend to replace RL2 of PCB1.

When ON/OFF accumulated occurred number of welding output exceeds 2,700,000, recommend to replace RL3 of PCB1.

#### 8. Outline Drawing- Hi400i

![](_page_44_Figure_8.jpeg)

### 7. Wire Feeder

#### 1. Specification

| Model                   | RF- Hi400               |
|-------------------------|-------------------------|
| Control method          | Communication (CAN)     |
| Motor spec. and control | DC24V / Encoder Control |
| Drive type              | 4Roll 4Geared           |
| Feeding speed           | 0.8~20 m/min            |
| Wire diameter           | 0.9, 1.0, 1.2mm         |
| Torch connection        | Asia Spec.              |
| Dimension (W*D*H)       | 192 * 242 * 197(mm)     |
| Weight                  | 6.1(Kg)                 |

#### 2. Installation

![](_page_45_Picture_4.jpeg)

- [1] Shock sensor cable connector : Connect the signal line of shock sensor.
- [2] Shielding gas connector : Connect the shielding gas hose of welding torch.
- [3] Inching switch : Feed the wire without generating the output.
- [4] (-) Sensing cable terminal : Connect the (-) voltage sensing cable from the workpiece.
- [5] Welding wire conduit cable connector : Connect the wire conduit cable from welding wire reel stand or wire spool of wire feeder.
- [6] Shielding gas connector : Connect the shielding gas hose from gas tank.
- [7] Welding torch connector : Connect the welding torch.
- $\ensuremath{[8]}$  (+) Output cable connector : Connect the (+) output cable from the welding power source.
- [MC4] Control cable connector : Connect the control cable from the welding power source.

#### 3. Parts List - RF- Hi400 Wire Feeder

![](_page_46_Figure_2.jpeg)

MOTOR

SOL V/V

**PCB11** 

**PCB12** 

Feeding motor

Gas valve

Control PCB

Drive PCB

40005684

45000448

45000474

45000475

ANKARSRUM-24V PM4228/181

DKC SD2002-02DN-02(24V)

HIFO500\_01

HIFO500\_02

1

1

1

1

#### 7. Wire Feeder

#### 4. Periodic Maintenance of parts according to Usage Time/Frequency

When accumulated operation time of the feeding motor exceeds 4,000 hours, check the condition of wire feeder roller, of the DRIVE ROLLER, and replace it if noise or friction occurs.

When accumulated operation time of the feeding motor exceeds 2,000 hours, check the wear on wire feeder roller by naked eyes and replace it if the wear condition is excessive.

When ON/OFF accumulated operation number of Solenoid Valve exceeds 5,400,000, recommend to replace SOL V/V.

### 7. Wire Feeder

5. Outline Drawing - RF- Hi400

![](_page_48_Figure_2.jpeg)

![](_page_48_Figure_3.jpeg)

#### 1. Regular Maintenance

|             | HAZARD   | Electric shock may result in death.   |
|-------------|--|---|
| A<br>X<br>N | <ul> <li>Before and after constatus during welding</li> <li>1) Be sure to work by</li> <li>2) For installation and at the input of the origination of the origination</li></ul> | nnecting the power source be sure to check the power source<br>g and voltage with a tester before working.<br>y a qualified electrician.<br>I maintenance inspection, be sure to cut off the power source<br>distribution switch board circuit protector before working for at<br>nce the voltage charged in the internal capacitor may remain,<br>harging voltage is discharged before working.<br>bower source and voltage before or after connecting the power<br>er before working. |

#### 2. Check in accordance with the Error Code

| Error Code | Cause   | Countermeasure  |
|------------|---|---|
| E01        | 3-Phase under input voltage<br>detection (-15% or less)   | 1. Check 3-Phase input voltage.<br>- Within ±15% of rated input voltage   |
| E02        | 3-Phase over input voltage<br>detection (+15% or more)  | 2. Replace PCB1.<br>3. Please contact our service team.   |
| E03        | <ul> <li>DC-LINK under voltage detection</li> <li>(264Vdc or less)</li> <li>J4(+)-J6(-) measured voltage of PCB2</li> <li>Rated input voltage AC 220V standard)</li> </ul>          | <ol> <li>Check 3- Phase input voltage.         <ul> <li>Within ±15% of rated input voltage</li> <li>Check F1(Fuse) from PCB2. Replace if damaged.</li> <li>Check the lighting status of LED2 from PCB2.</li> <li>Check the lighting status of LED1 from PCB2.</li> <li>LED lights on within about 1 minute after first power on.</li> </ul> </li> <li>Replace PCB1.</li> <li>Replace PCB2.</li> <li>Please contact our service team.</li> </ol> |
| E04        | <ul> <li>DC-LINK over voltage detection</li> <li>(358Vdc or more)</li> <li>J4(+)-J6(-) measured voltage of</li> <li>PCB2</li> <li>Rated input voltage AC 2200V standard)</li> </ul> | <ol> <li>Check 3 phase input voltage.</li> <li>Within ±15% of rated input voltage</li> <li>Replace PCB1.</li> <li>Replace PCB2.</li> <li>Please contact our service team.</li> </ol>  |
| E05        | DC-LINK(primary side) over<br>current error   | <ol> <li>Check F1(Fuse) from PCB2. Replace if<br/>damaged.</li> <li>Replace PCB1.</li> <li>Replace PCB2.</li> <li>Please contact our service team.</li> </ol>   |
| E06        | No load voltage output detection  | <ol> <li>Check the connection status of '+ /- sensing line.</li> <li>Check the connection status of control cable.<br/>(Welding power source ↔ wire feeder)</li> <li>Damage to the power part is suspected. Please contact our service team.</li> </ol>   |
| E07        | No output voltage is detected during<br>welding   | <ol> <li>Check the connection status of '+ /- sensing line.</li> <li>Check the connection status of control cable.<br/>(Welding power source ↔ wire feeder)</li> <li>Replace PCB1.</li> <li>Please contact our service team.</li> </ol>   |

| E08 | No output current detected for more<br>than 2 seconds during welding   | <ol> <li>Check if wire remains.</li> <li>check the condition of work piece such as burn<br/>through.</li> <li>Check an abnormality in the feeding of<br/>wire.         <ul> <li>Check the operation of wire feeder.</li> <li>Check whether there is an excessive Feeding<br/>Load, and take action when a Load occurs.</li> </ul> </li> <li>In case of repeated occurrence, please contact<br/>our service team.</li> </ol>   |
|-----|--|---|
| E09 | Welding output over current error  | <ol> <li>Select proper welding condition (CTWD,<br/>synergic database)</li> <li>Check short circuit for output(+) / (-) terminal or<br/>between cables.</li> <li>Check short circuit of tip and work piece<br/>during welding operation.</li> <li>Check if speed of feeding motor controls<br/>correctly. (Check if the feeding speed set during<br/>inching operation matches the actual speed.)</li> <li>Check the wire harness demage or connection<br/>of CT2 - PCB1 J10.</li> <li>Replace CT2.</li> <li>Replace PCB1.</li> <li>Please contact our service team.</li> </ol> |
| E10 | Reserved   | Reserved  |
| E11 | PCB1 power under voltage detection<br>- 19.2Vdc or less<br>- 21(+)-GM(-) measured voltage<br>after separation of PCB1 J1 | <ol> <li>Check 3- phase input voltage.         <ul> <li>Within ±15% of rated input voltage</li> <li>Replace VS1 if it is less than the reference voltage of the measured voltage.</li> <li>Replace PCB1.</li> <li>Please contact our service team.</li> </ul> </li> </ol>   |
| E12 | PCB1 power over voltage detection<br>- 28.8Vdc or more<br>- 21(+)-GM(-) measured voltage<br>after separation of PCB1 J1  | <ol> <li>Check 3- phase input voltage.         <ul> <li>Within ±15% of rated input voltage</li> <li>Replace VS1 if it is more than the reference voltage of the measured voltage.</li> <li>Please contact our service team.</li> </ul> </li> </ol>  |
| E13 | PCB3 Power under voltage detection<br>- 19.2Vdc or less<br>- 21(+)-GM(-) measured voltage<br>after separation of PCB3 J1 | <ol> <li>Check 3- phase input voltage.         <ul> <li>Within ±15% of rated input voltage</li> <li>Replace VS1 if it is less than the reference voltage of the measured voltage.</li> <li>Replace PCB3.</li> <li>Please contact our service team.</li> </ul> </li> </ol>   |

|     | PCB3 power over voltage detection   | 1. (        | Check 3-phase input voltage.                 |
|-----|---|-------------|--|
|     | 29 8V/de er mere  | -           | Within $\pm 15\%$ of rated input voltage     |
| E14 |   | 2. F        | Replace VS1 if it is more than the reference |
|     | - 21(+)-Givi(-) Theasured Voltage   | ١           | voltage of the measured voltage.             |
|     | alter separation of PCB3 J1   | 3. F        | Please contact our service team.             |
|     |   | 1. (        | Check 3-phase input voltage.                 |
|     | Cooling fan power under voltage   | -           | Within $\pm 15\%$ of rated input voltage     |
|     | detection   | 2. F        | Replace VS1 if it is less than the reference |
| E15 | - 19.2Vdc or less   | ١           | voltage of the measured voltage.             |
|     | - 22(+)-GM(-) measured voltage  | 3. F        | Replace cooling fan (FAN1, FAN2).            |
|     | after separation of PCB1 J1   | 4.F         | Replace PCB1.                                |
|     |   | 5. F        | Please contact our service team.             |
|     | Cooling fan power over voltage  | 1. (        | Check 3-phase input voltage.                 |
|     | detection   | -           | Within $\pm 15\%$ of rated input voltage     |
| E16 | - 28.8Vdc or more   | 2. F        | Replace VS1 if it is more than the reference |
|     | - 22(+)-GM(-) measured voltage  | ١           | voltage of the measured voltage.             |
|     | after separation of PCB1 J1   | 3. F        | Please contact our service team.             |
|     |   | 1. (        | Check 3-phase input voltage.                 |
|     | PCB5 power under voltage detection  | -           | Within $\pm 15\%$ of rated input voltage     |
| F17 | - 19.2Vdc or less   | 2. F        | Replace VS1 if it is less than the reference |
| E., | - 76(+)-GM(-) measured voltage  | ١           | voltage of the measured voltage.             |
|     | after separation of PCB5 J1   | 3. F        | Replace PCB5.                                |
|     |   | 4. F        | Please contact our service team.             |
|     | PCB5 power over voltage detection   | 1. (        | Check 3-phase input voltage.                 |
|     | - 28.8Vdc or more   | -           | Within $\pm 15\%$ of rated input voltage     |
| E18 | - 76(+)-GM(-) measured voltage  | 2. F        | Replace VS1 if it is more than the reference |
|     | after separation of PCB5 J1   | \           | voltage of the measured voltage.             |
|     | $1 \text{ and } y \text{ obtains a detection or region of } \pm 15 \text{ V}$ | 3. F        | Please contact our service team.             |
| E10 | Low voltage detection ends of + 15v   | 1. F        | Replace PCB1.                                |
| EIS |   | 2. F        | Please contact our service team.             |
|     | Overvoltage detection error of $\pm 15V$                                      |             |  |
| F20 | auxiliary power on welding main   | 2. F        | Replace PCB1.                                |
| LLU | control PCB   | 2. F        | Please contact our service team.             |
|     | Low voltage detection error of + 15V  |             |  |
| E21 | auxiliary power on welding main   | 3.F         | Replace PCB1.                                |
|     | control PCB.  | 2. F        | Please contact our service team.             |
|     | Overvoltage detection error of +15V   | 1 Г         | Poplace BCB1                                 |
| E22 | auxiliary power on welding main   | ו. ר<br>ס ר | Place FODT.                                  |
|     | control PCB.  | 2. г        | lease contact our service team.              |
|     |   | 1. (        | Check whether the torch signal is applied.   |
|     | When the welding power source is  | -           | Check whether the torch signal is applied of |
| E23 | turned on while the torch signal is   | t           | torch signal input external device (Hi-COMM  |
|     | applied   | (           | Channel 1, 2, wire feeder)                   |
|     |   | 2. F        | Please contact our service team.             |

|     |  | 1. Check that the welding start time is within 10  |
|-----|--|--|
|     |  | seconds after the welding torch signal.  |
| E24 | No load output continuous (more<br>than 10 seconds) error before<br>welding current detection                                  | <ul> <li>2. Check if wire remains.</li> <li>3. Check an abnormality in the feeding of wire.</li> <li>- Check the operation of wire feeder.</li> <li>- Check whether there is an excessive feeding load, and take action when a load occurs.</li> </ul> |
|     |  | 4. In case of repeated occurrence, please contact  |
|     | Welding power internal right high  | our service team.  |
| E27 | temperature error  |  |
| E28 | Welding power internal MOSFET<br>high temperature error (over load)  | 1. Use at ambient temperature (40°C) or less.  |
|     | Welding power internal left high   | 2. Please keep the proper installation distance of   |
| E29 | temperature error  | the welding machine for ventilation.   |
| E30 | Welding power internal output diode<br>high temperature error (over load)  | 3. Use it according to the rated duty cycle (60% 400A).  |
| E31 | Welding power internal main<br>transformer high temperature error<br>(over load)   | <ul><li>4. Check the operation of cooling fan (FANI, FAN2).</li><li>5. Replace PCB1.</li><li>6. Please contact our service team.</li></ul>   |
| E32 | Welding power internal upside high<br>temperature error  |  |
| E33 | Daisy chain1 recognition error<br>- Poor connection status of wire<br>harness connector of main PCB<br>of welding power source | <ol> <li>Check the connection of the wire harness<br/>connector connected to PCB in the welding power<br/>source.</li> <li>PCB1 CN2/PCB5 CN2/CN4/CN5/PCB7 CN2/CN3</li> <li>Please contact our service team.</li> </ol>                                 |
| E34 | Daisy chain2 recognition error<br>- Poor connection status of wire<br>harness connector of main PCB<br>of welding power source | <ol> <li>Check the connection of the wire harness<br/>connector connected to PCB in the welding power<br/>source.</li> <li>PCB1 CN3/PCB5 CN3/CN6/PCB8 CN1/PCB7 CN4</li> <li>Please contact our service team.</li> </ol>                                |
| E35 | Cooling fan relay operation error  | 1. Replace PCB1.   |
|     | Cooling fan (FAN1) operation error   | 1. Check the presence of any foreign substances in   |
| E36 | <ul> <li>If the cooling fan does not run for<br/>more than 3 seconds</li> </ul>  | the cooling fan.   |
| E37 | Cooling fan (FAN2) operation error<br>- If the cooling fan does not run for<br>more than 3 seconds                             | <ol> <li>Check the accumulated operation time of the cooling fan. (Refer to 6-6 of this manual)</li> <li>Replace the non-operating cooling fan (FAN1 or FAN2)</li> <li>Replace PCB1</li> </ol>   |

| E38 | Welding control PCB NVSRAM no<br>response error  | <ol> <li>Initialize the welding machine (Refer to<br/>5-2-2 of this manuel)</li> <li>Replace PCB1.</li> <li>Please contact our service team.</li> </ol>   |
|-----|--|---|
| E39 | Internal CAN communication error   | 1. Please contact our service team.   |
| E40 | Internal RS-232 communication<br>error   | 1. Please contact our service team.   |
| E41 | Wire feeder under input voltage<br>detection<br>- 40.8Vdc or less<br>- 75(+)-GM(-) measured voltage<br>after separating PCB11 J1 | <ol> <li>Check the connection of control cable (welding power source ↔ wire feeder)</li> <li>Check 3- phase input voltage.         <ul> <li>Within ±15% of rated input voltage</li> <li>Replace VS1 if it is more than the reference voltage of the measured voltage.</li> <li>Replace PCB11.</li> <li>Please contact our service team.</li> </ul> </li> </ol>  |
| E42 | Wire feeder over input voltage<br>detection<br>- 55.2Vdc or less<br>- 75(+)-GM(-) measured voltage<br>after separating PCB11 J1  | <ol> <li>Check the connection of control cable (welding<br/>power source ↔ wire feeder)</li> <li>Check 3- phase input voltage.         <ul> <li>Within ±15% of rated input voltage</li> <li>Replace VS1 if it is less than the reference<br/>voltage of the measured voltage.</li> <li>Please contact our service team.</li> </ul> </li> </ol>  |
| E43 | Wire feeder motor over current<br>detection  | <ol> <li>Check an abnormality in the feeding of wire.</li> <li>Check the operation of wire feeder.</li> <li>Check whether there is an excessive feeding<br/>load (transformation of torch liner (bending),<br/>etc), and take action when a load occurs.</li> <li>Check that the hole size of the contact tip<br/>matches the wire diameter being used.</li> <li>Replace PCB12.</li> <li>Replace MOT OR.</li> <li>Please contact our service team.</li> </ol> |
| E44 | Wire feeder motor encoder error  | <ol> <li>Check the connection of PCB12 CN1<br/>connector, MOTOR encoder connector, and<br/>wiring.</li> <li>Replace PCB11.</li> <li>Replace PCB12.</li> <li>Please contact our service team.</li> </ol>   |

|     |                                    | <ol> <li>Check the shock sensor alarm status.</li> <li>Check the operation sensor of shock sensor</li> </ol> |
|-----|------------------------------------|--|
|     |                                    | within robot motion range.   |
|     |                                    | - Torch length (short) or shock sensor alarm   |
| E45 | Wire feeder shock sensor error     | during robot movement  |
|     |                                    | 3. Check the wire connection of shock sensor.  |
|     |                                    | - Normal when cable is connected to contact B  |
|     |                                    | 4. Replace PCB11.  |
|     |                                    | 5. Please contact our service team.  |
|     |                                    | 1. Check the connection of control cable. (welding   |
|     |                                    | power source ↔ wire feeder)  |
|     |                                    | 2. Check the connection of the wire harness  |
| E/6 | Wire feeder CAN communication      | connector connected to the PCB in the wire   |
| L40 | error                              | feeder.  |
|     |                                    | - PCB11 CN12   |
|     |                                    | 3. Replace PCB11.  |
|     |                                    | 4. Please contact our service team.  |
|     |                                    | 1. Select the proper welding condition. (CTWD,   |
|     |                                    | synergic database).  |
|     |                                    | 2. Check the short circuit for output(+)/(-)   |
|     | Main TR primary side over current  | terminal or between cables.  |
| E47 | Detection                          | - Make sure not to emerge short circuit.   |
|     |                                    | 3. Check the short circuit of tip and work piece   |
|     |                                    | during welding operation.  |
|     |                                    | 4. In case of repeated occurrence, please contact  |
|     |                                    | our service team.  |
|     |                                    | 1. Check the connection of the Hi-COMM interface   |
| E48 | Hi-COMM channel 1 error            | cable connected to channel 1.  |
|     |                                    | 2. Replace Hi-COMM.  |
|     |                                    | 1. Check the connection of the HI-COMM interface   |
| E49 | Hi-COMM channel 2 error            | cable connected to channel 2.  |
|     |                                    | 2. Replace Hi-COMM.  |
| E50 | Reserved                           | Reserved   |
| E51 | Switching frequency under          | 1. Replace PCB1.   |
|     | detection                          | 2. Please contact our service team.  |
| E52 | Switching frequency over detection | I. Replace PUBI.   |
|     |                                    | 2. Please contact our service team.  |

#### 3. Product Firmware Update

To update the welding machine's firmware, the welding power-integrated firmware file (Hi400i\_Ver\_\*.\*.\*.hwf) and USB flash memory are required.

After connecting the USB flash memory to the USB port of the PC, format (FAT32) as follows.

| USB 드라이브 (F:) 형식 | ×      |
|------------------|--------|
| 용량(P):           |        |
| 14.5GB           | ~      |
| 파일 시스템(F):       |        |
| FAT32(기본값)       | ~      |
| 할당 단위 크기(A):     |        |
| 기본 할당 크기         | ~      |
| 포맷 옵션(O)         |        |
| 포맷 옵션(O)         |        |
| ☑ 빠른 포맷(Q)       |        |
|                  |        |
|                  |        |
| 1174/C)          | FF71/C |
| A144(5)          | =/(C)  |
|                  |        |

If you insert the USB flash memory with the firmware stored in the USB port of the welding power source front panel, alarm UPDATE LED status in front after 10 seconds and the firmware update will proceed automatically. Firmware update proceeds in the order of welding control PCB, interface PCB, and HMI.

![](_page_56_Picture_6.jpeg)

![](_page_57_Picture_1.jpeg)

When the welding power source internal PCB firmware update is completed, all status LED are lighted on. When the status of LED stays on for more than 3 seconds, the USB flash memory is automatically rebooted and the firmware update is completed.